



Neural Global Shutter

Learn to Restore Video from a Rolling Shutter Camera with Global Reset Feature

Zhixiang Wang

Xiang Ji

Jia-Bin Huang

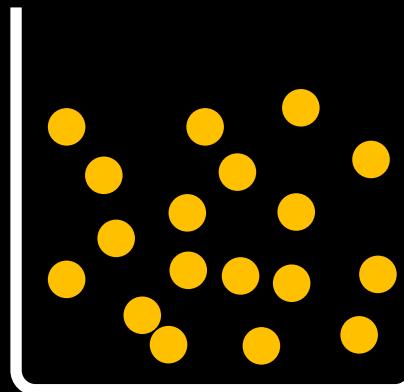
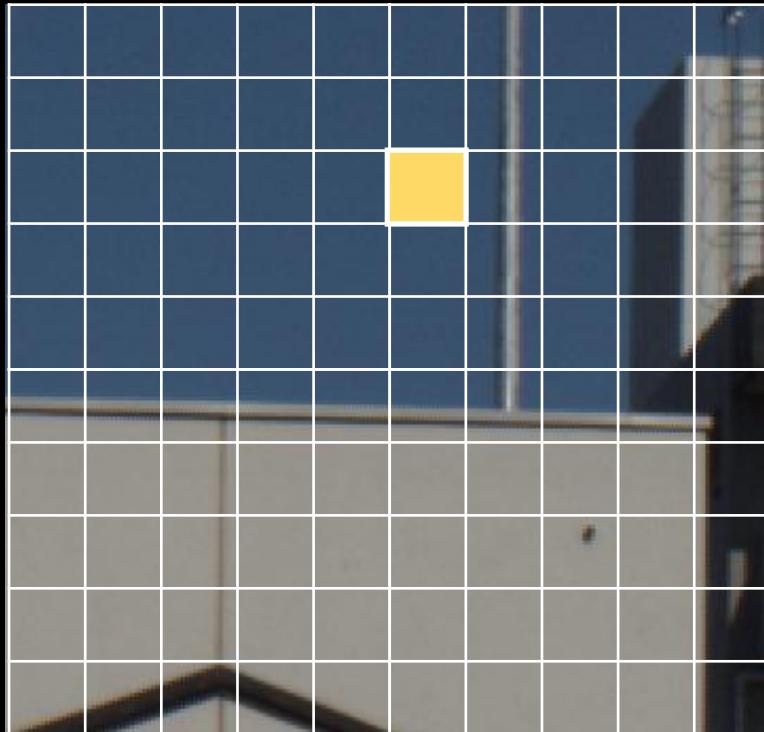
Shin'ichi Sato

Xiao Zhou

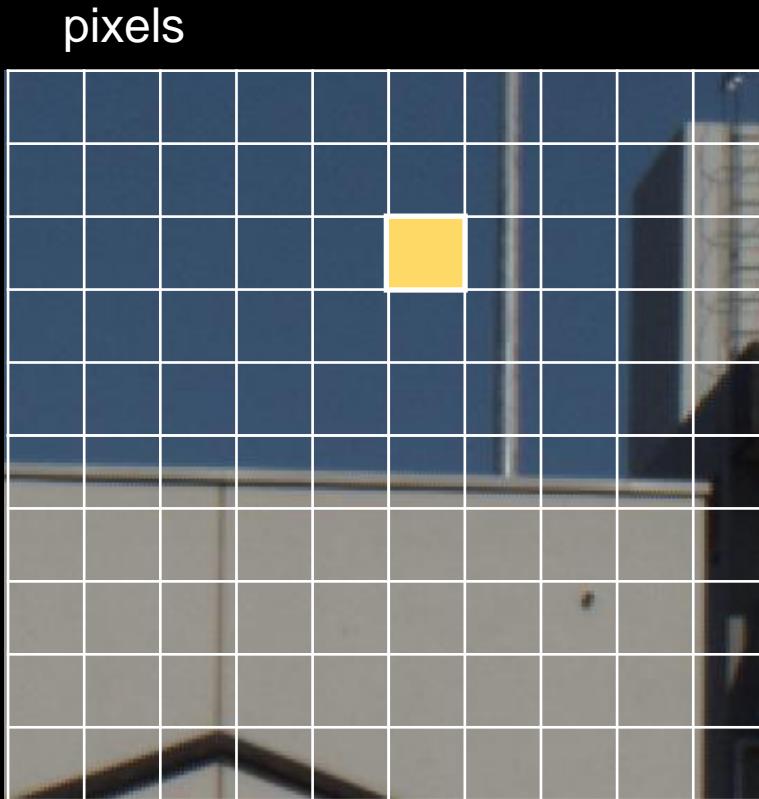
Yinqiang Zheng

How do image sensors record photon?

pixels



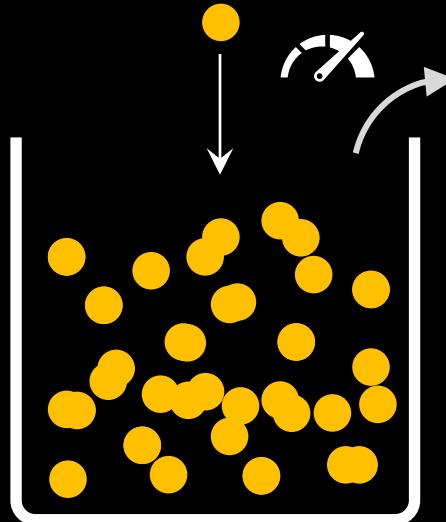
How do image sensors record photon?



reset

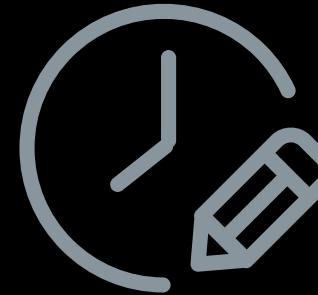
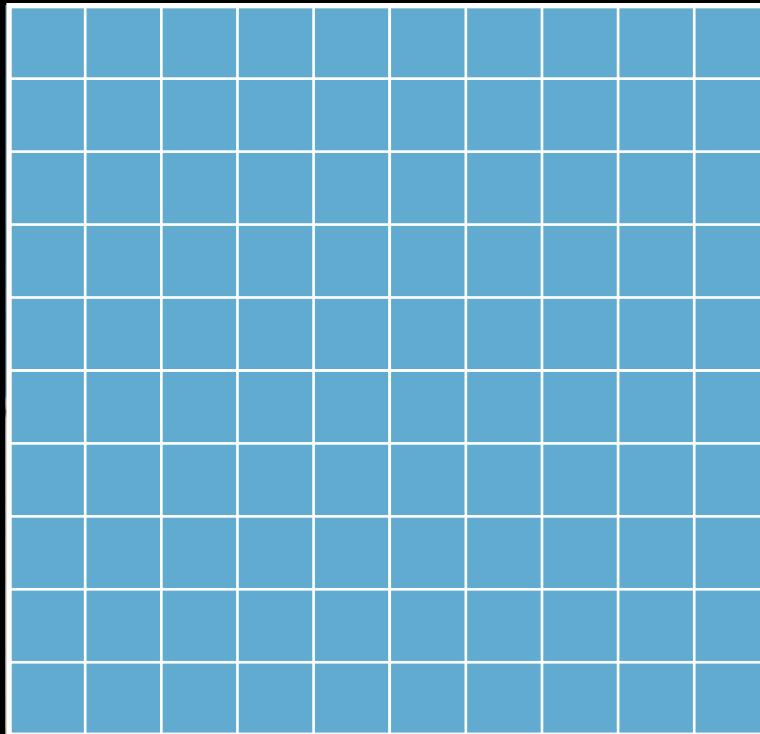


exposure

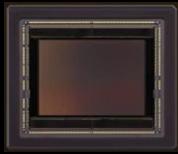


How do image sensors record photon?

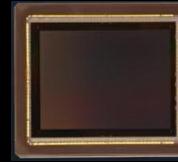
pixels



Two common shutter modes

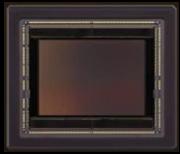


Global shutter

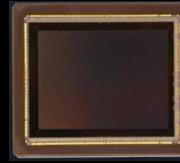


Rolling shutter

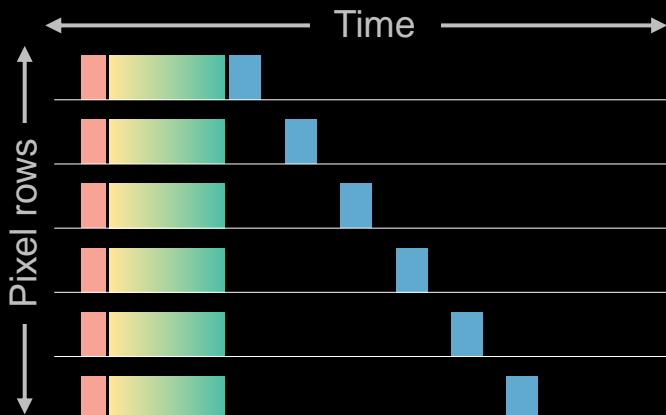
Two common shutter modes



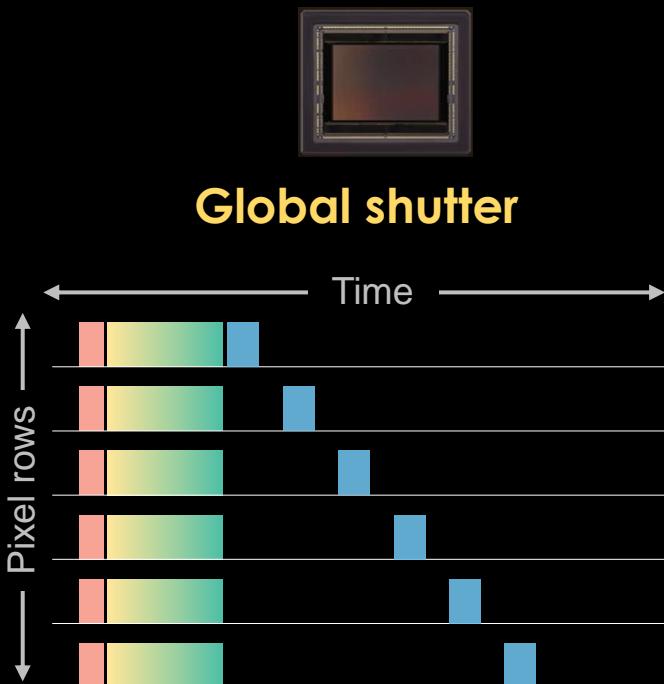
Global shutter



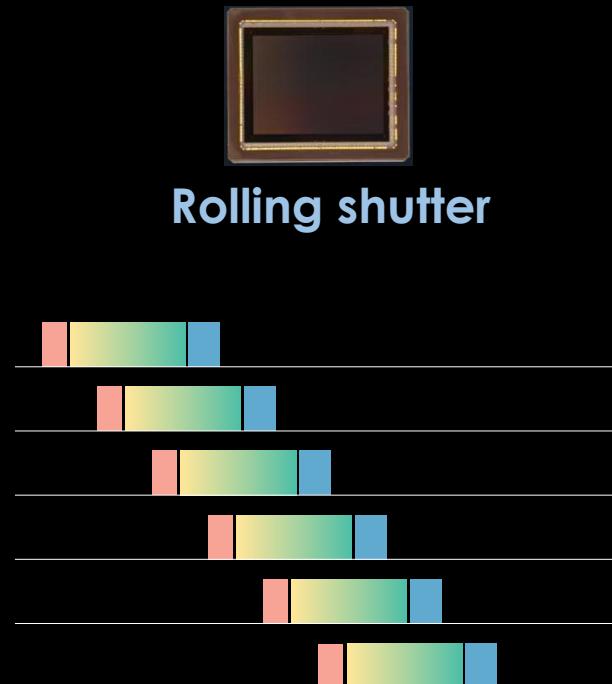
Rolling shutter



Two common shutter modes

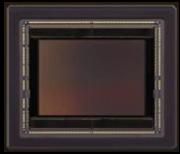


Global shutter

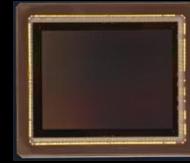
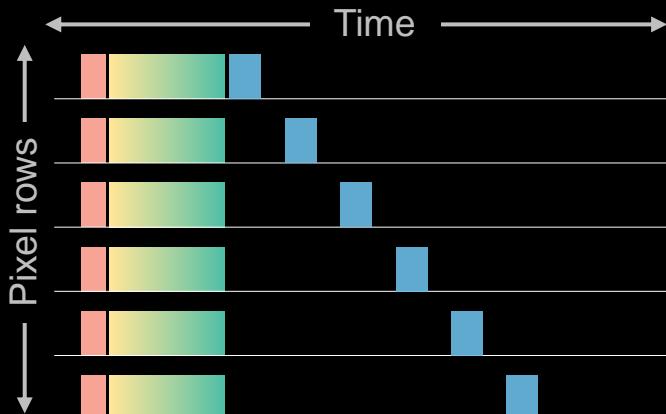


Rolling shutter

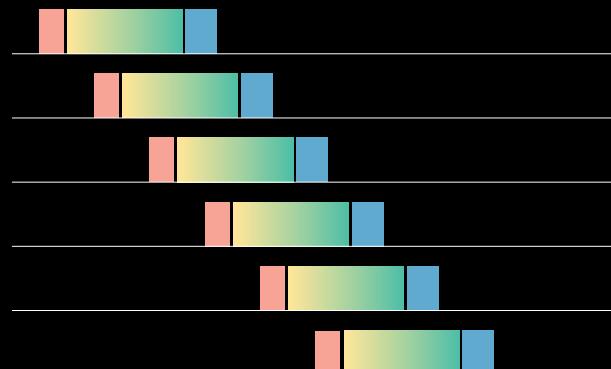
Two common shutter modes



Global shutter

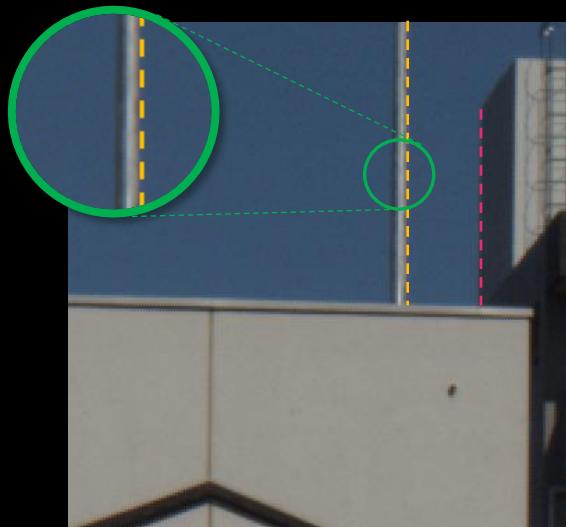
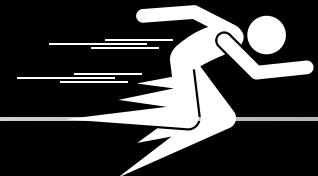


Rolling shutter [most used]

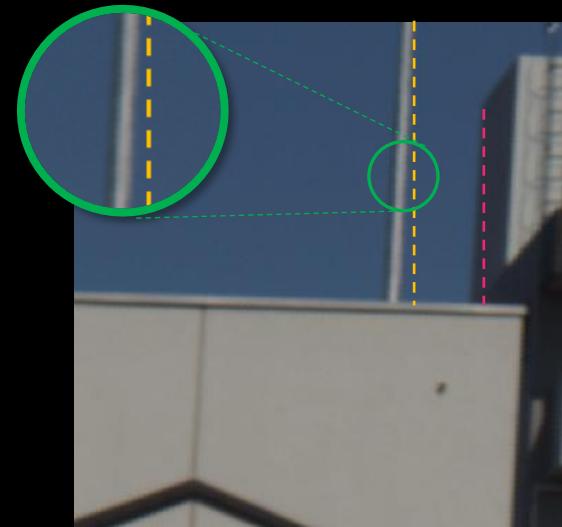


Advantages: *low cost, low noise, high sensitivity and high frame rate*

The problem of rolling shutter



global shutter



rolling shutter

Geometry distortion

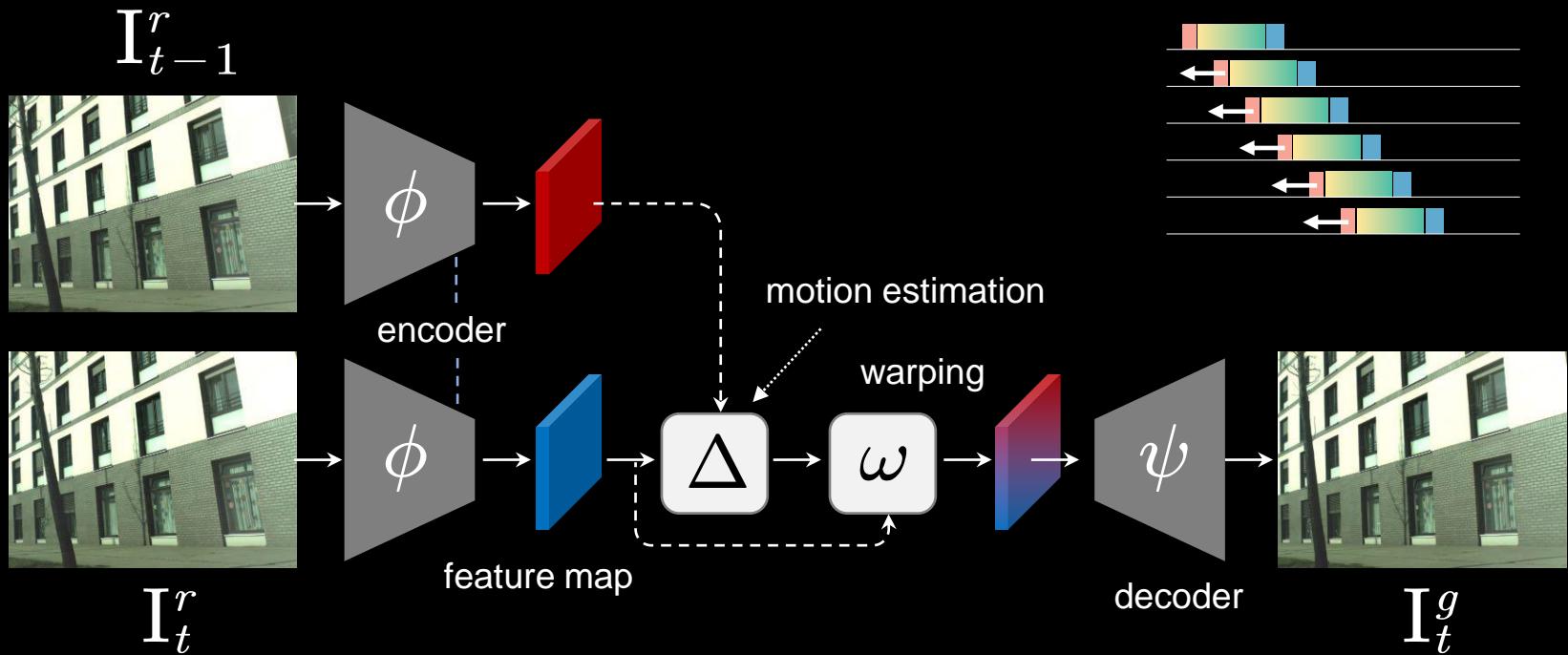
The problem of rolling shutter



Example: automatic car



Correcting rolling shutter distortion



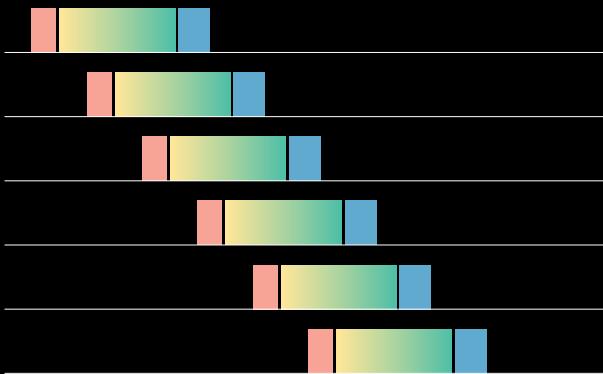
Correcting rolling shutter distortion

Limitations

1. Rely on prior assumptions on scene/motion
2. Motion compensation steps are either oversimplified or computationally inefficient

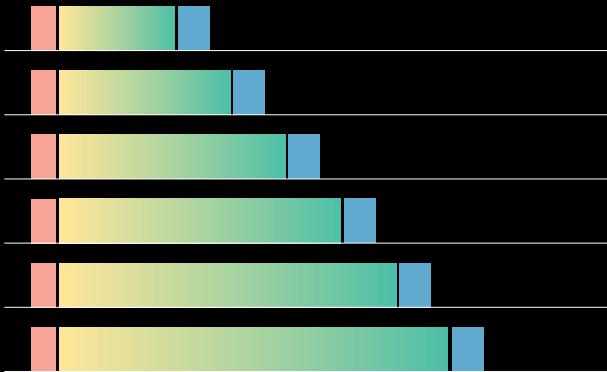
Our finding – a widely ignored feature

rolling shutter



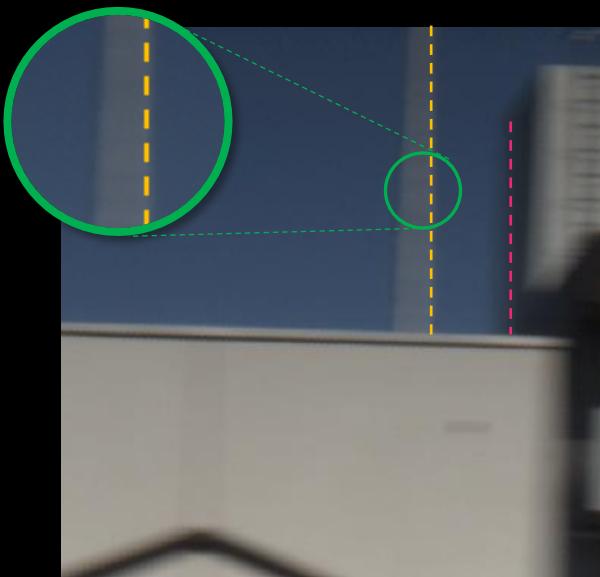
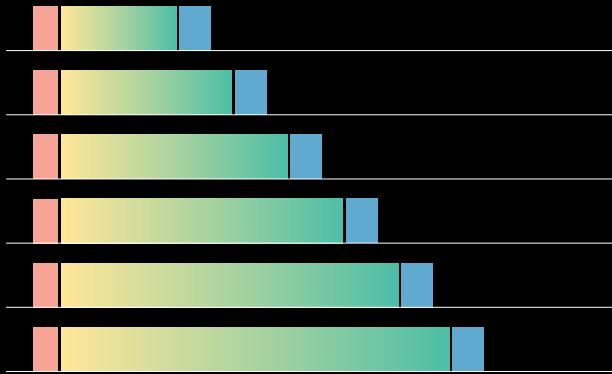
Our finding – a widely ignored feature

rolling shutter with global reset

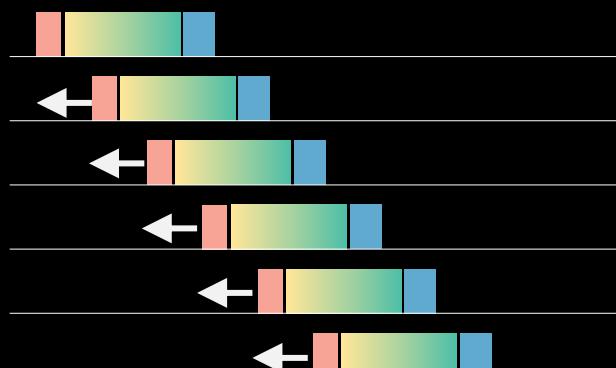


Our finding – a widely ignored feature

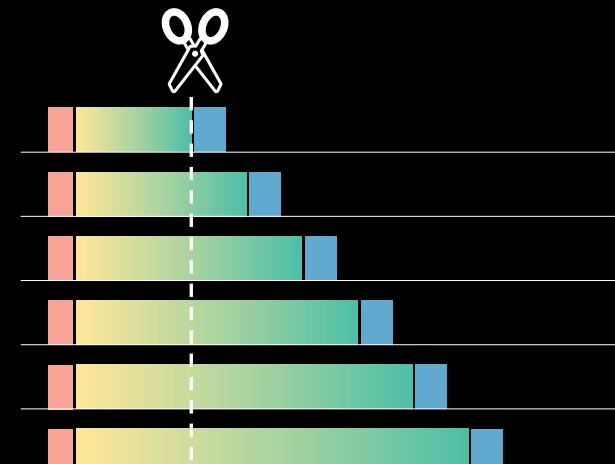
rolling shutter with global reset



Our idea – alleviating RSGR distortion

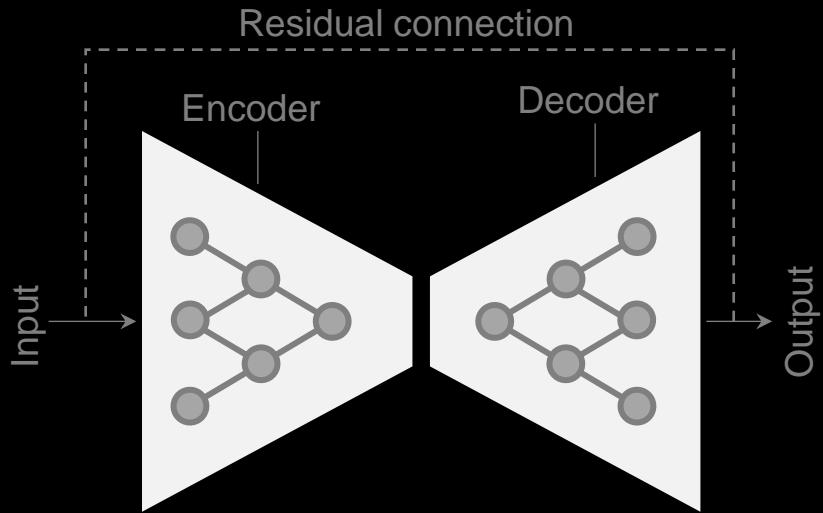


Conventional RS correction

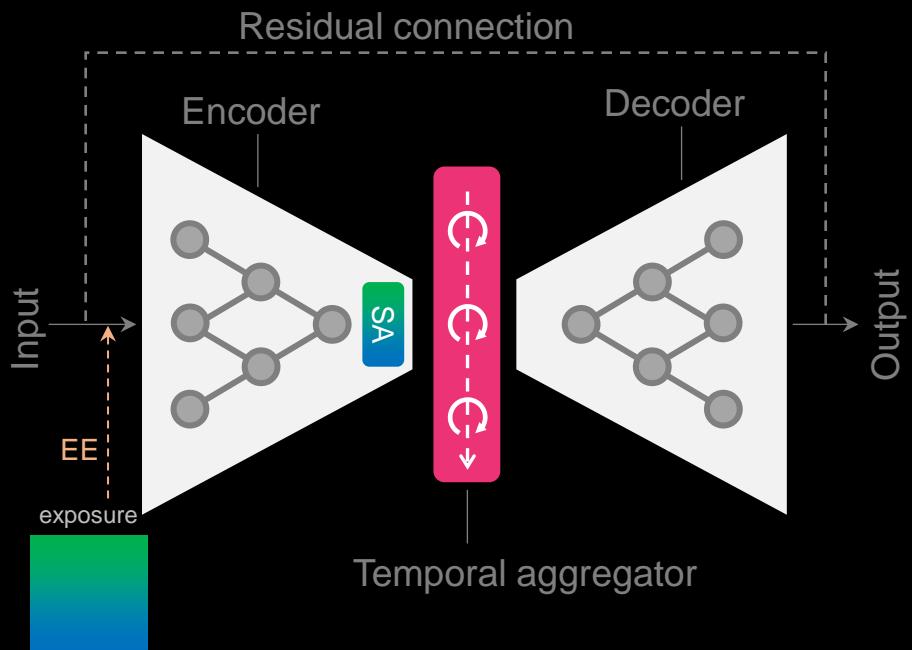


Ours: deblur-like

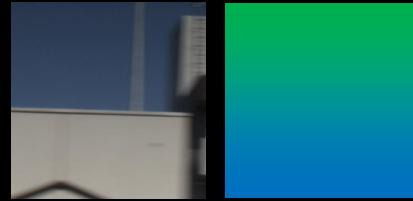
Our method – model



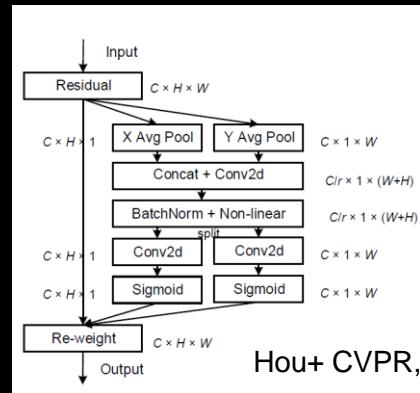
Our method – model



Exposure encoding

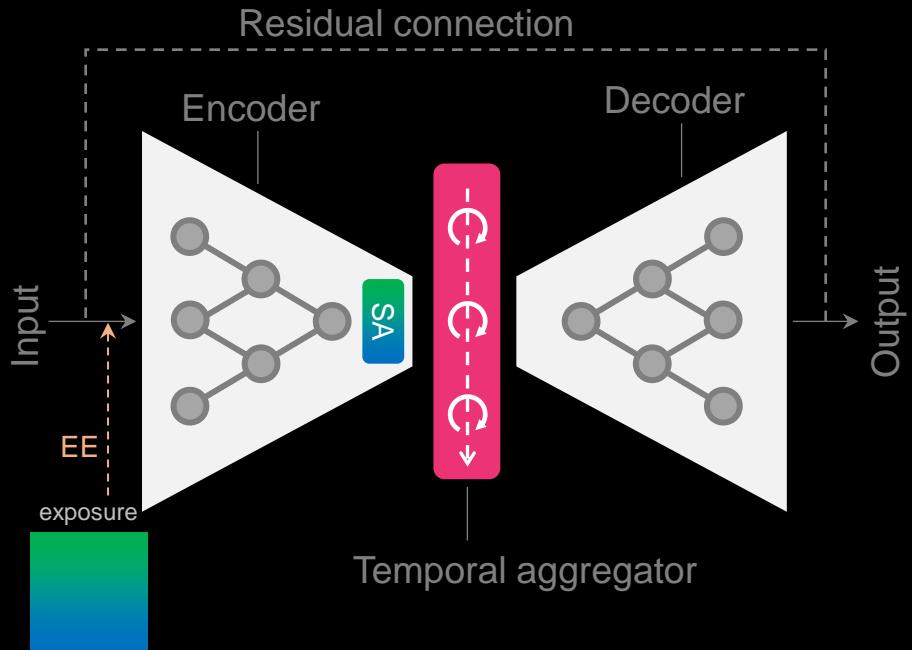


Spatial attention

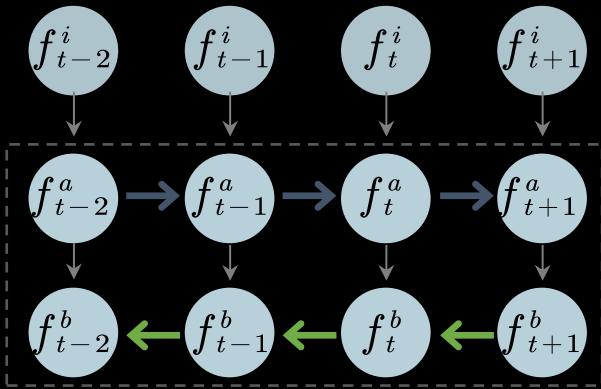


Hou+ CVPR, 2021]

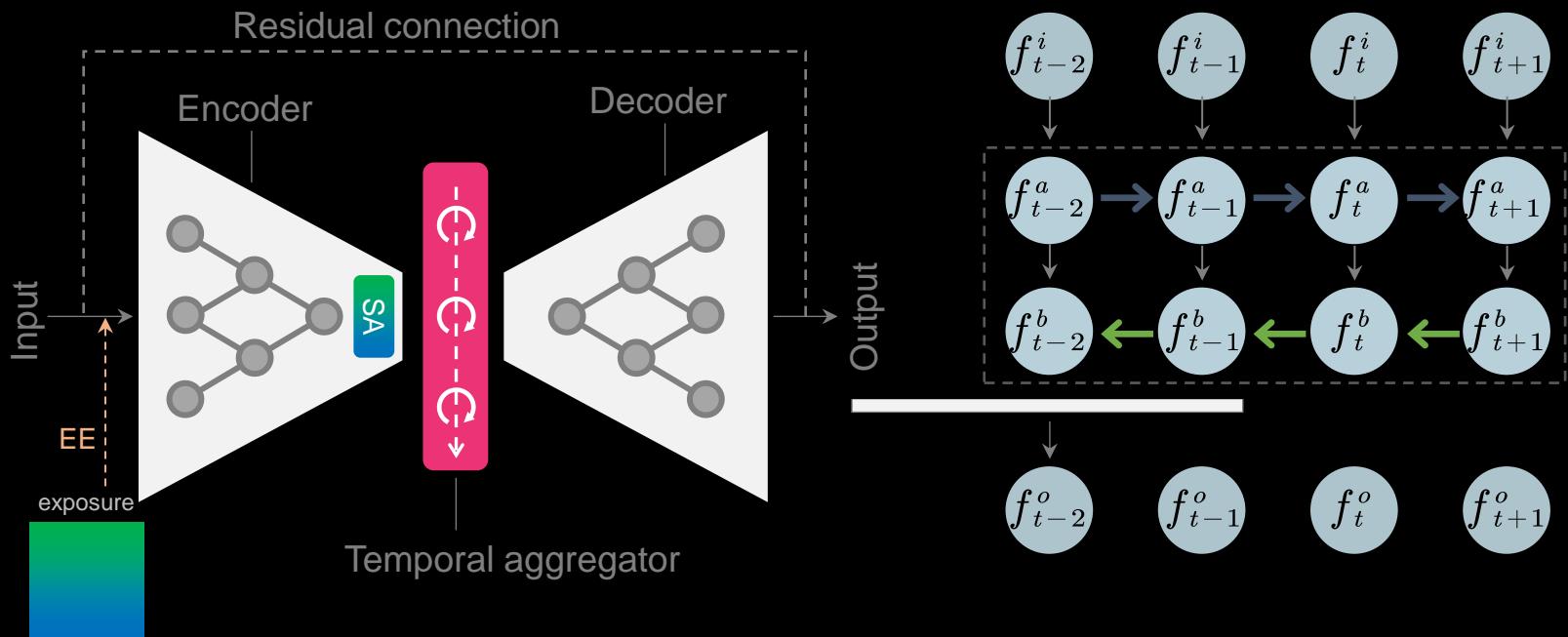
Our method – model



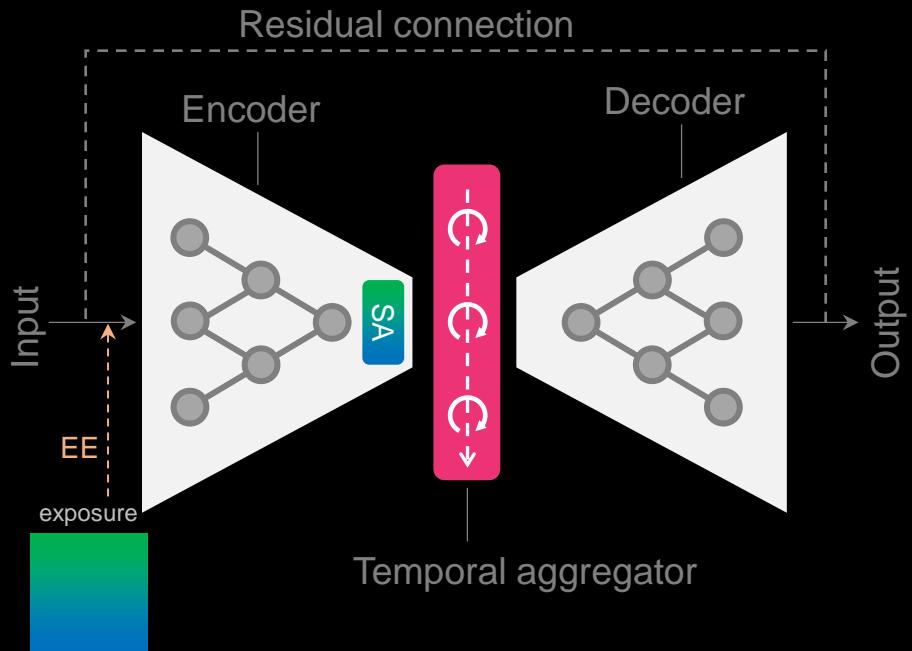
Long-term temporal aggregator



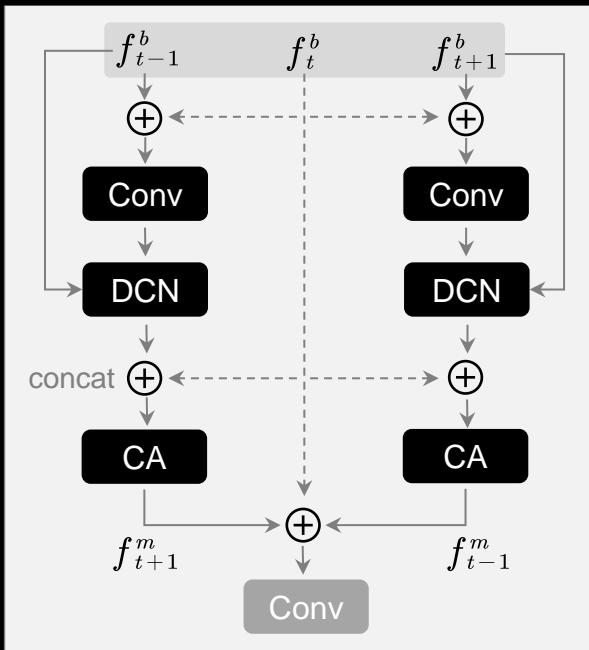
Our method – model



Our method – model

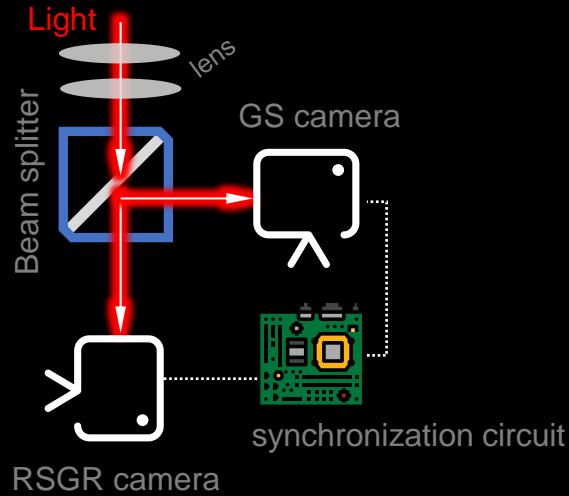


Short-term temporal aggregator

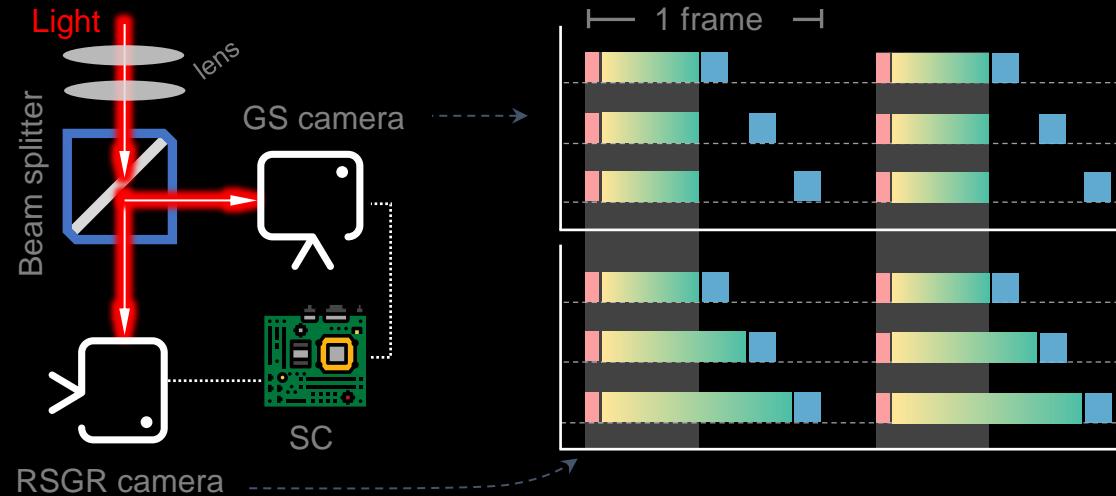


Our method – data acquisition

Our method – data acquisition



Our method – data acquisition



Results – video



input



output



ground-truth

Results – sample frame



input



output

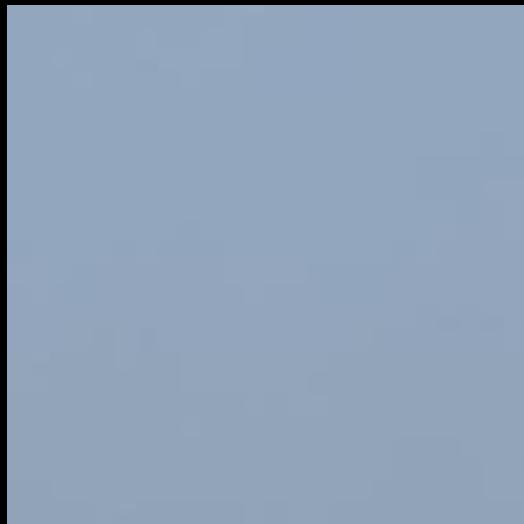


ground-truth

Results – zoom in



input



output



ground-truth

Results – qualitative comparisons

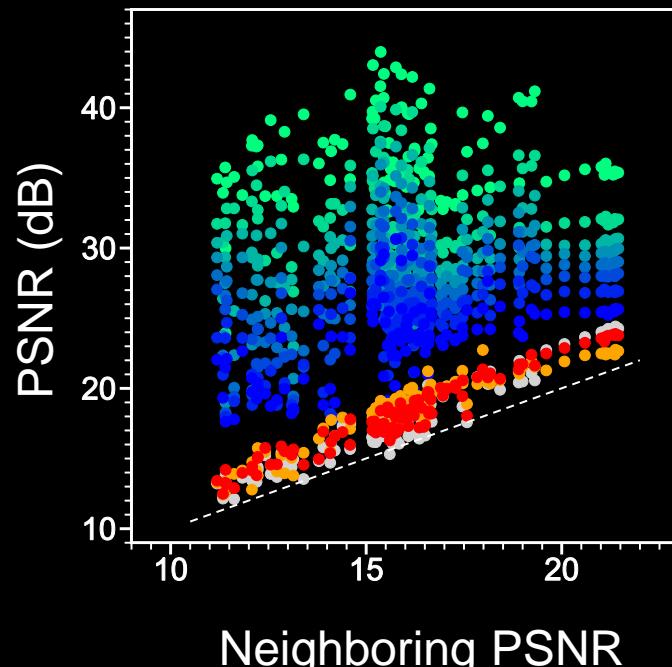


Results – quantitative comparisons

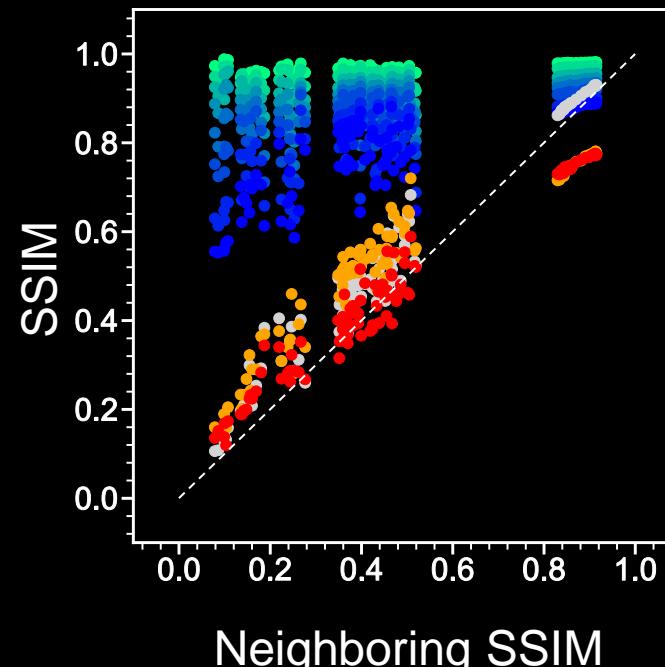
Method	Set-I				Set-II			
	Full	Top	Middle	Bottom	Full	Top	Middle	Bottom
Input	18.95 / 0.75	25.32 / 0.82	21.56 / 0.81	16.36 / 0.63	17.82 / 0.73	23.64 / 0.77	21.45 / 0.77	15.54 / 0.66
deblurGANv2	19.97 / 0.73	21.54 / 0.75	23.73 / 0.77	18.17 / 0.69	18.34 / 0.69	20.14 / 0.69	22.14 / 0.71	17.28 / 0.66
SRN	26.87 / 0.86	26.12 / 0.83	27.08 / 0.85	29.59 / 0.89	25.05 / 0.81	24.32 / 0.79	25.65 / 0.81	27.02 / 0.83
STRCNN	24.88 / 0.85	24.27 / 0.83	25.33 / 0.85	27.54 / 0.88	22.59 / 0.81	22.99 / 0.79	23.46 / 0.81	23.66 / 0.83
DBN	26.49 / 0.87	26.50 / 0.85	26.66 / 0.87	28.47 / 0.89	22.57 / 0.81	23.24 / 0.80	23.81 / 0.81	23.24 / 0.82
IFIRNN	28.01 / 0.89	27.20 / 0.88	28.35 / 0.89	29.21 / 0.90	25.17 / 0.82	24.77 / 0.80	25.62 / 0.81	26.94 / 0.84
ESTRNN	25.85 / 0.89	26.67 / 0.88	30.16 / 0.90	25.19 / 0.89	22.72 / 0.83	23.42 / 0.81	26.03 / 0.83	22.86 / 0.83
DSUR	24.72 / 0.84	24.30 / 0.81	25.65 / 0.85	26.63 / 0.86	22.50 / 0.80	22.49 / 0.78	23.87 / 0.81	23.38 / 0.83
JCD	28.15 / 0.85	27.50 / 0.84	28.73 / 0.85	30.44 / 0.87	25.33 / 0.80	24.77 / 0.78	25.71 / 0.80	27.43 / 0.83
Ours-noT	27.56 / 0.85	26.23 / 0.83	27.55 / 0.85	31.55 / 0.88	25.37 / 0.80	24.74 / 0.77	25.65 / 0.79	27.29 / 0.82
Ours	32.72 / 0.92	31.83 / 0.92	33.01 / 0.92	34.65 / 0.92	27.29 / 0.85	26.96 / 0.84	27.57 / 0.85	28.35 / 0.86

Results – comparison with RS solution

Training ξ : 0.001  0.01 — RSGR Input — - RS Input — - Pre-trained DSUR — - Fine-tuned DSUR



[Liu+ CVPR, 2020]



Results – comparison with RS solution

Method	Time/frame
Zhuang+	400.00 sec
DSUR	0.43 sec
JCD	0.83 sec
Ours	0.04 sec

Thank you!



<https://lightchaserx.github.io/>

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code and data

<https://github.com/lightChaserX/neural-global-shutter>

